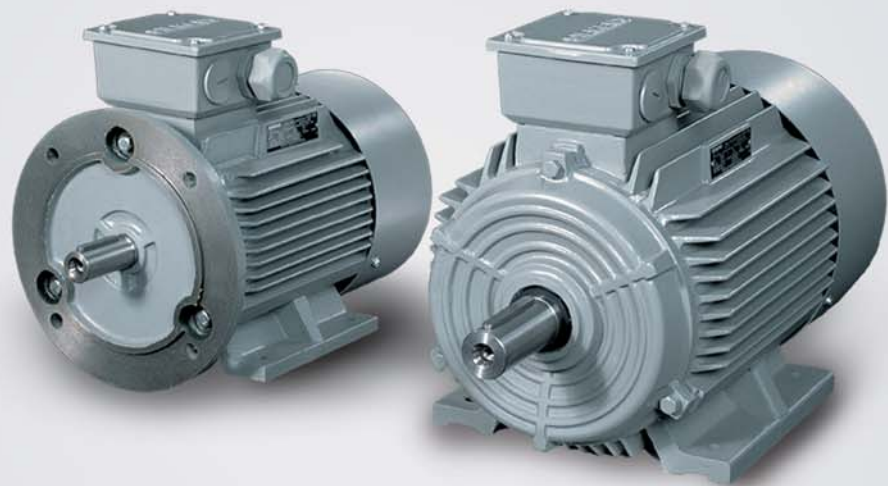


Low-voltage motors up to 315kW

Catalog D81.5 • 11.2010



1LG0 Low-voltage Motors

Answers for industry.

SIEMENS

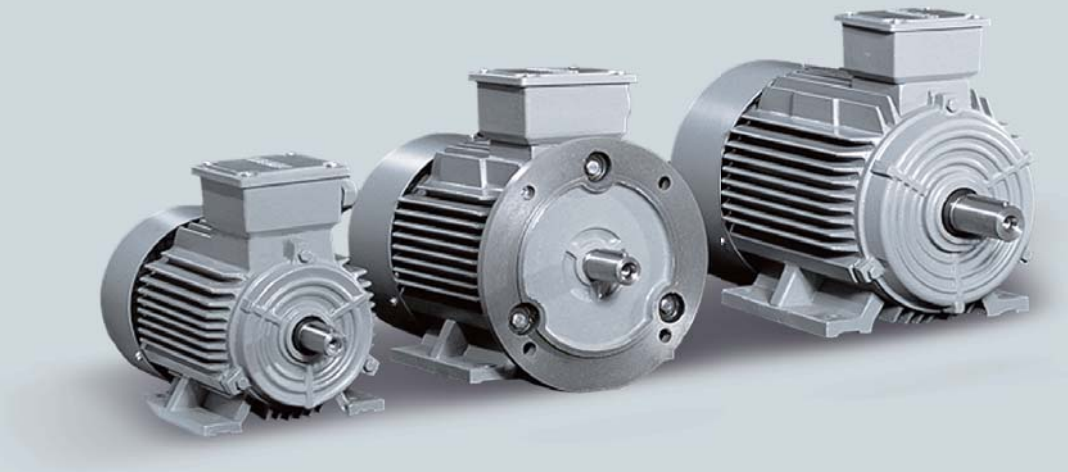


Table of Contents

Overview	3
Motor standards	5
Mechanical design	6
Electrical design	10
Converter fed application	11
MLFB configuration	12
Options	13
Technical data	14
Dimension drawings	20
Technical supporting documentation	36
Certificates	37



Overview

The 1LG0 series of 3 phase asynchronous motors are Totally Enclosed Fan Cooled (TEFC) with IP55 environmental protection. These motors are designed and manufactured in accordance with ISO, IEC standards.

Features of Siemens 1LG0 series

- Frame and terminal box material: Grey cast iron
- Standard colour: Stone Grey RAL 7030
- Available in 2,4,6 pole variants with efficiency class IE1 according to IEC60034-30
- Specific wound stators supporting multiple 3PH mains supply voltages at 50Hz or 60Hz
- Frame sizes: 80mm ~ 355mm
- Rated power range: 0.55kW ~ 315kW at 50Hz
- Standard mounting types and variations (IEC 60034-7)
- TEFC with IP55 degree of protection (IEC 60034-5)
- Overload capacity of 1.5 times rated current for 2 minutes (IEC 60034-1)
- V-ring as standard on DE rotor shaft for motor with FS 80 ~ 132, and oil seal as option; Oil seal as standard for motor with FS160 and above
- Anti-condensation heater (space heater) as option
- Winding protection with PTC and PT100 as option
- Insulation class: F, used according to temperature rise B

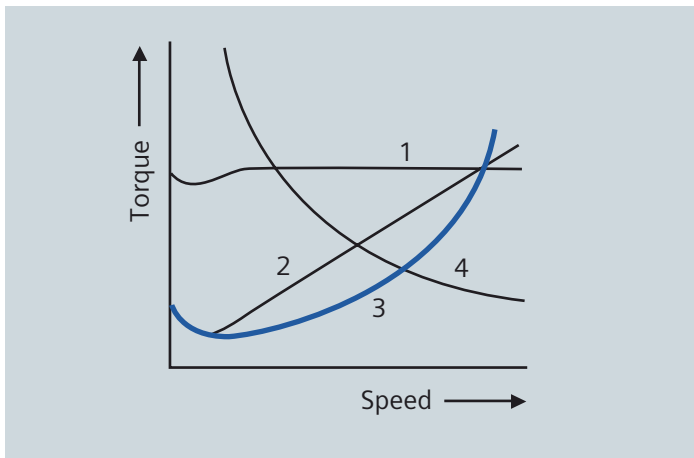
¹⁾ FS, abbreviation of "Frame size".

- Flexible cable entry (Rotatable terminal box)
- Rotor shaft with closed keyway (A type key) and NDE shaft extension
- Dynamically balanced rotor with a half key
- Drain plug on FS 160 ~ 355 motor as standard

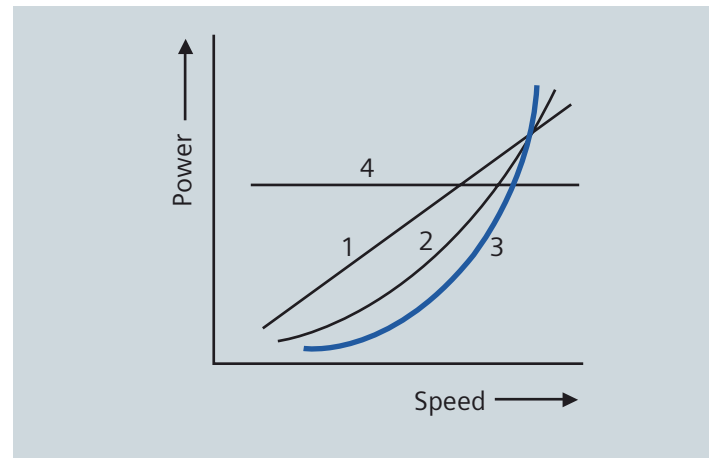
- Ribbed end shields for better bearing heat dissipation and prolonged bearing life
- Lubrication of bearing
 - FS 80 ~ 160 motor - greased for life
 - FS 180 ~ 280 motor - regreasable when ordered with K40 option
 - FS 315 ~ 355 motor - with regreasing device as standard

The 1LGO is a General Purpose Motor with cast iron frame designed for constant or adjustable speed with continuous duty operation (S1) requiring variable torque over a speed range.

Load torque characteristics



Torque / speed characteristic



Power / speed characteristic

1. Torque almost constant; power proportional to speed.

2. Torque increases proportionally with the speed; power proportional to the square of the speed.

3. Torque increases proportionally with the square of the speed; power proportional to the cube of the speed. (applicable for 1LGO series motors)

4. Torque decreases in inverse proportion to the speed; power constant.



1LGO motors are suitable for pumps, fans, compressors and HVAC applications where variable or constant speed is required (Curve 3). For more demanding applications we recommend Siemens consultation.

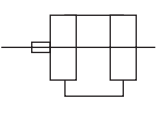
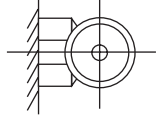
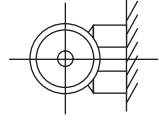
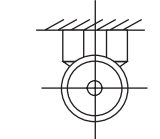
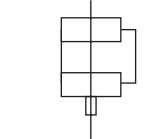
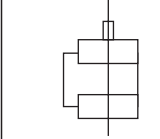
Mechanical design

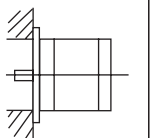
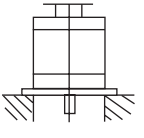
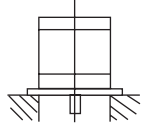
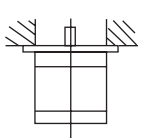
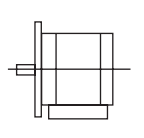
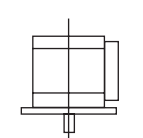
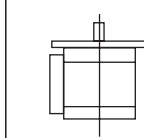
Terminal box

Terminal boxes are top mounted as default on the motor. This box can be rotated by 4 X 90° to allow for cable entry from each direction. In addition the terminal box can be installed either on the Left Hand Side (LHS – code K10) or Right Hand Side (RHS – code K09) when viewed from the drive end (DE) side of the motor.

Type	Frame Size	Protection degree	Rotation of terminal box	Number of cable grand	Terminal box materia	Terminal bus	Max. cable size (mm ²)	Cable entry size
1LG0	80	IP55	4 x 90°	2	Cast-iron	M4	2.5	M24 x 1.5 + M16 x 1.5
	90	IP55	4 x 90°	2	Cast-iron	M5	2.5	M24 x 1.5 + M16 x 1.5
	100	IP55	4 x 90°	2	Cast-iron	M5	4	M24 x 1.5 + M16 x 1.5
	112	IP55	4 x 90°	2	Cast-iron	M5	4	2 – M32 x 1.5
	132	IP55	4 x 90°	2	Cast-iron	M5	6	2 – M32 x 1.5
	160	IP55	4 x 90°	2	Cast-iron	M6	16	2 – M36 x 2
	180	IP55	4 x 90°	2	Cast-iron	M6	16	2 – M36 x 2
	200	IP55	4 x 90°	2	Cast-iron	M8	25	2 – M48 x 2
	225	IP55	4 x 90°	2	Cast-iron	M8	35	2 – M48 x 2
	250	IP55	4 x 90°	2	Cast-iron	M10	120	2 – M64 x 2
	280	IP55	4 x 90°	2	Cast-iron	M10	120	2 – M64 x 2
	315	IP55	4 x 90°	2	Cast-iron	M16	240	2 – M64 x 2
	355	IP55	4 x 90°	2	Cast-iron	M20	400	2 – M72 x 2

Construction or mounting type

Construction type	With feet and without flange on the end-shield (DE)					
Mounting type	IM B3 FS 80 ~ 355	IM B6 FS 80 ~ 160	IM B7 FS 80 ~ 160	IM B8 FS 80 ~ 160	IM V5 FS 80 ~ 225	IM V6 FS 80 ~ 225
Diagram						

Construction type	Without feet and with flange on the end-shield (DE)			With feet and with flange on the end-shield (DE)			
Mounting type	IM B5 FS 80 ~ 280	IM V1 ¹⁾ FS 80 ~ 355		IM V3 FS 80 ~ 160	IM B35 FS 80 ~ 355	IM V15 FS 80 ~ 160	IM V36 FS 80 ~ 160
Diagram							

¹⁾ For IMV1 with canopy and without canopy, motor has different order number. Please find detailed information in "Technical data table".

Bearing

All motors are supplied with the ball bearing as standard. These bearings are either of the sealed or regreasable type.

Bearing design

- Floating bearing situated at DE & NDE of FS 80 ~ 160 motor;
- Fixed bearing situated at DE of FS 180 ~ 355 motor with IM B3, IM B5;
- Fixed bearing situated at DE of FS 180 ~ 225 motor with IM V1;
- Fixed bearing situated at NDE of FS 250 ~ 355 motor with IM V1;

Bearing type

Type	Frame Size	Poles	Drive-end bearing		Non-drive-end bearing	
			Horizontal mounting	Vertical mounting	Horizontal mounting	Vertical mounting
1LGO	80	2, 4, 6	6204 2RZC3		6204 2RZC3	
	90	2, 4, 6	6205 2RZC3		6205 2RZC3	
	100	2, 4, 6	6206 2RZC3		6206 2RZC3	
	112	2, 4, 6	6206 2RZC3		6206 2RZC3	
	132	2, 4, 6	6208 2RZC3		6208 2RZC3	
	160	2	6209 2RZC3		6209 2RZC3	
		4, 6	6309 2RZC3		6209 2RZC3	
	180	2	6211 C3		6211 C3	
		4, 6	6311 C3		6211 C3	
	200	2	6312 C3		6212 C3	
		4, 6	6312 C3		6212 C3	
	225	2	6312 C3		6312 C3	
		4, 6	6313 C3		6312 C3	
	250	2	6313 C3		6313 C3	7313AC
		4, 6	6314 C3		6313 C3	7313AC
	280	2	6314 C3		6314 C3	7314AC
		4, 6	6317 C3		6314 C3	7314AC
	315	2	6317 C3		6317 C3	7317AC
		4, 6	6319 C3		6319 C3	7319AC
	355	2	6319 C3		6319 C3	7319AC
		4, 6	6322 C3		6322 C3	7322AC

Bearing life

Frame Size	Poles	Bearing lifetime ¹⁾
80 ~ 355	2, 4, 6	20000 or 40000 ²⁾ (hours)

¹⁾ Lifetime means that motor runs under normal operation, maintained according to operating manual.

²⁾ 40000Hrs applies for horizontally installed motors with coupling output without additional axial loads and at least 20,000 hours with the admissible permitted loads.

Grease life and Relubrication interval (for horizontal installation)

Please refer to 1LGO series motor operating instruction for grease life and relubrication interval (for horizontal installation)

If the coolant temperature is increased by 10°C, the grease lifetime and regreasing interval is halved. Operating the 1LGO motor beyond the rated speed will increase the mechanical stress on the motor resulting in increased vibrations, reduced bearing and grease lifespan.

Cooling and ventilation

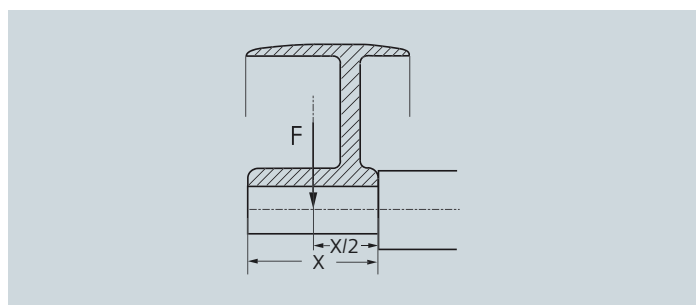
The 1LG0 standard motors from FS 80 ~ 355 are fitted with an radial flow fan for cooling in accordance with IEC 60034-6 cooling method.

Permissible Radial forces (F) on the DE rotor shaft

The table below contains the permissible Radial Force values in Newtons with the assumption of zero axial forces.

Frame Size	Poles	Radial force, in: N
80	2	640
	4	800
	6	920
90	2	700
	4	870
	6	1,000
100	2	970
	4	1,205
	6	1,390
112	2	1,240
	4	1,550
	6	1,790
132	2	1,485
	4	1,685
	6	2,156
160	2	1,570
	4	1,925
	6	2,125
180	2	3,010
	4	3,695
	6	4,290

Frame Size	Poles	Radial force, in: N
200	2	4,035
	4	4,830
	6	5,520
225	2	4,420
	4	5,450
	6	6,160
250	2	5,035
	4	6,190
	6	7,060
280	2	3,690
	4	9,220
	6	10,525
315	2	3950
	4	9,900
	6	12,109
355	2	6,500
	4	10,400
	6	12,500



Permissible radial force "F" (N) applied at X/2 (mm) to shaft shoulder

Noise levels

The table below contains noise level for the 1LG0 unloaded motors taken at 50Hz operation.

And all published values here have a tolerance of +3dB.

Output (kW)	synchronous speed (r/min)		
	L_{pfa} / L_{WA} (dB (A))		
	3000 (2 poles)	1500 (4 poles)	1000 (6 poles)
0.55	–	47 / 58	42 / 54
0.75	56 / 67	47 / 58	45 / 57
1.1	56 / 67	49 / 61	45 / 57
1.5	60 / 72	49 / 61	49 / 61
2.2	60 / 72	52 / 64	53 / 65
3	64 / 76	52 / 64	57 / 69
4	65 / 77	53 / 65	57 / 69
5.5	68 / 80	59 / 71	57 / 69
7.5	68 / 80	59 / 71	61 / 73
11	73 / 86	63 / 75	61 / 73
15	73 / 86	63 / 75	61 / 73
18.5	73 / 86	64 / 76	64 / 76
22	75 / 89	64 / 76	64 / 76
30	78 / 92	66 / 79	64 / 76
37	78 / 92	68 / 81	66 / 78
45	78 / 92	68 / 81	68 / 80
55	79 / 93	70 / 83	68 / 80
75	80 / 94	73 / 86	73 / 85
90	80 / 94	73 / 86	73 / 85
110	82 / 96	80 / 93	73 / 85
132	82 / 96	80 / 93	73 / 85
160	85 / 98	84 / 94	80 / 92
200	85 / 98	84 / 94	80 / 92
220	89 / 103	88 / 101	80 / 92
250	89 / 103	88 / 101	N / A
280	89 / 103	88 / 101	N / A
315	89 / 103	88 / 101	N / A

L_{pfa} – sound pressure level

L_{WA} – sound power level

Vibration

1LG0 rotors are dynamically balanced to severity grade A using a half key.

Table below contain the effective vibration values for unloaded motors.

Vibration grade	Frame size (mm)	$56 \leq FS \leq 132$	$160 \leq FS \leq 280$	$280 < FS \leq 355$
A	Mounting	Vibration velocity (mm/s)	Vibration velocity (mm/s)	Vibration velocity (mm/s)
	Free suspension	1.6	2.2	2.8
	Rigid mounting	1.3	1.8	2.3

Electrical design

Reliable quality and performance

To ensure reliable and long life, the 1LG0 windings are made of materials with class F temperature rise limited to class B (80K) .

Voltage and Frequency

1LG0 standard motor will operate on main power supplies in accordance with IEC 60034-1 Category A (combination of voltage deviation $\pm 5\%$ and frequency deviation $\pm 2\%$) for voltage and frequency fluctuations.

Rated Output

1LG0 rated output power refers to continuous duty (S1) operation in accordance with IEC 60034-1 when operated at 40°C ambient temperature and at site altitudes of 1000m or less.

1LG0 current overload is in accordance with IEC 60034-1 (1.5 times for 2 minutes) when operated as per the rated nameplate data.

Environmental

- Suitable for IP55 installations
- Below or equal to 1000m above sea level
- Operating temperature between -20°C and 40°C
- Relative humidity

Temperature	Relative humidity
-20°C ≤ T ≤ 20°C	100%
20°C < T ≤ 30°C	95%
30°C < T ≤ 40°C	55%

Note: For other requirements, Siemens should be consulted.

If environmental conditions vary from those listed above, please consult the chart below for output power derating factor.

	< 30°C	30 ~ 40°C	45°C	50°C	55°C	60°C
1000 m	1.07	1.00	0.96	0.92	0.87	0.82
1500 m	1.04	0.97	0.93	0.89	0.84	0.79
2000 m	1.00	0.94	0.90	0.86	0.82	0.77
2500 m	0.96	0.90	0.86	0.83	0.78	0.74
3000m	0.92	0.86	0.82	0.79	0.75	0.70
3500 m	0.88	0.82	0.79	0.75	0.71	0.67
4000 m	0.82	0.77	0.74	0.71	0.67	0.63

Space heater (Option code: K45) electrical data

Frame Size	80 ~ 90	100 ~ 112	132 ~ 160	180 ~ 200	225 ~ 280	315	355
Power (W)	20	30	40	50	60	80	110
Voltage (V)	220						

Converter fed application

1LG0 motors from FS 80 ~ 250 are suitable for converter fed operation in variable torque (VT) applications. When 1LG0 motor is operated with a converter, the motor must be ordered with winding protection options such as PTC, PT100.

Note:

- Insulated bearing is not available as an option for the 1LG0 motors. This must be taken into consideration during selection and configuration.
- In application where the motor is driven by a converter, the degree of electrical interference depends on the type of converter used (type, number of IGBTs, interference suppression measures, and manufacturer), cabling, distance and application requirements.
- The installation guidelines of the converter manufacturer with regards to electromagnetic compatibility must be considered at all times during the design and implementation phases.

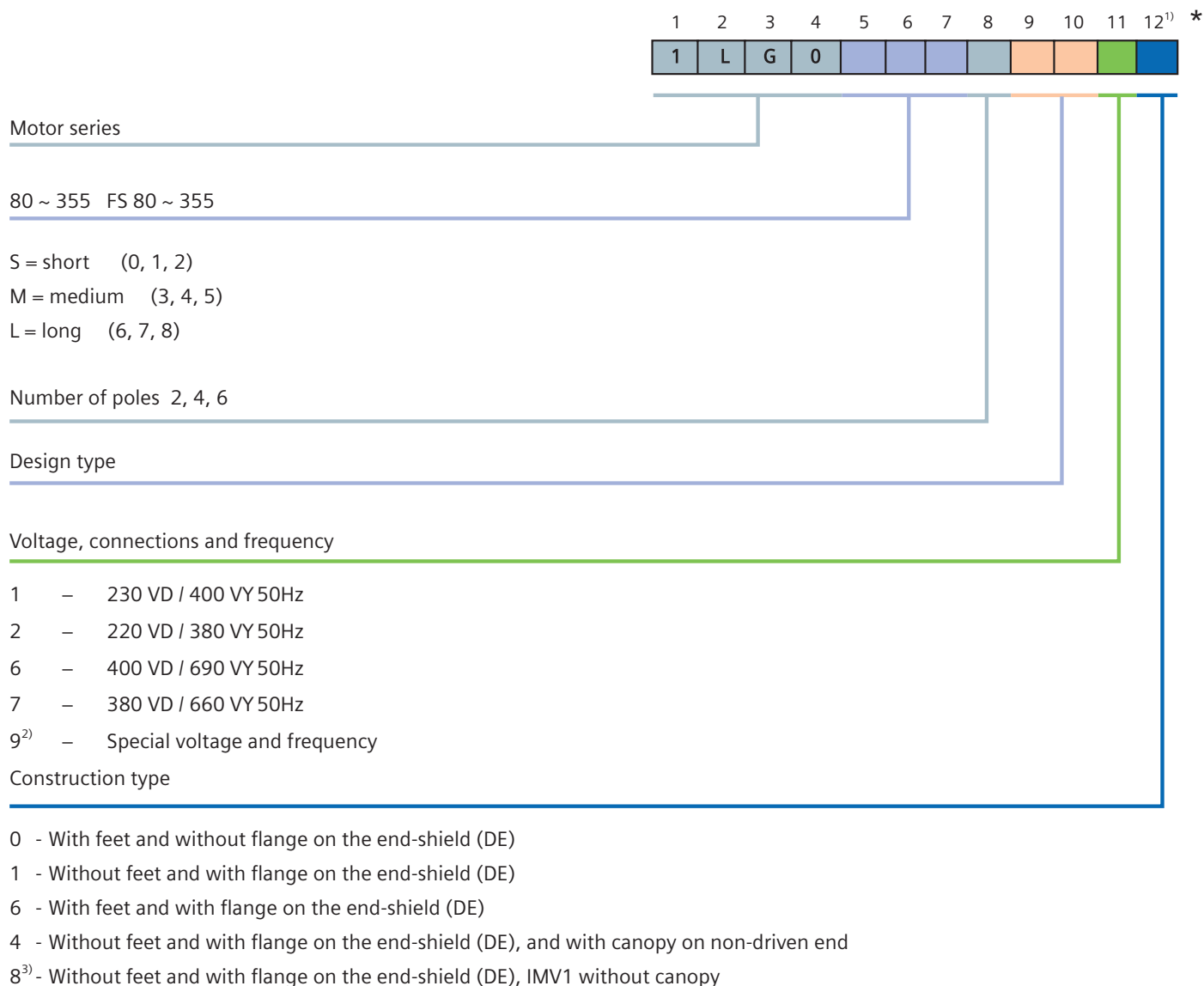
Nameplate Overview

- Rated voltage
- Rated frequency
- Rated output
- Rated speed
- Efficiency
- Power factor
- Connection type
- Protection degree
- Series number
- Motor type
- Balance
- Insulation class
- Weight

SIEMENS		3~Mot.	1LG0183-2AA70-Z	EFF2	CE
LMH	/		/		Q/321081KYA04-2006
IP55	180M	IMB3	165kg	BRG DE	6211 C3 BRG NDE 6211 C3 Thcl.F
50HZ	380/660V	Δ/Y		60HZ	440V Δ
22kW	41.3/23.8A			24.5kW	39.7A
EFF.91.2%	COS φ 0.89	2940r/min		EFF.90%	COS φ 0.90 3540r/min
360-400/630-690V	Δ/Y			420-460V Δ	(H)
39.1-43.5/22.7-24.8A				38.0-41.6A	
SIEMENS STANDARD MOTORS LTD.					



MLFB configuration



Ordering example:

Three-phase motor IP55

2-pole 50 Hz, 11kW 380VD/660VY IMB3

Order No. 1LG0163-2AA..

Voltage identifier: 7

construction type identifier: 0

¹⁾ Option codes are added after position 12;

²⁾ When selecting special voltage and frequency mentioned in "option" part, 11 position of MLFB should be changed to "9".

³⁾ Code "8" is only applicable to 1LG0 motor from FS 250 ~ 355, 1LG0 motor with FS 250 ~ 355, IMV1 without canopy; for 1LG0 motor with the other frame sizes, IMV1 without canopy, the 12th position is "1".

Options

Option Code	Description	Application Scope
Special voltage and frequency		
L1C	415VY 50Hz, 50Hz output	FS 80 ~ 355
L1D	415VD 50Hz, 50Hz output	FS 80 ~ 355
L1U	400VD 50Hz, 50Hz output	FS 80 ~ 355
L2B	220VD / 380VY 60Hz, 60Hz output	FS 80 ~ 355
L2D	380VD / 660VY 60Hz, 60Hz output	FS 80 ~ 355
L2E	460VY 60Hz, 60Hz output	FS 80 ~ 355
L2F	460VD 60Hz, 60Hz output	FS 80 ~ 355
Electrical design		
A11	Motor protection with PTC thermistors with three embedded temperature sensors for tripping	FS 80 ~ 355
A12	Motor protection with PTC thermistors with six embedded temperature sensors for alarm and tripping	FS 80 ~ 355
A60	Installation of 3 PT100 resistance thermometers	FS 100 ~ 355
A61	Installation of 6 PT100 resistance thermometers	FS 180 ~ 355
A72	Installation of 2 PT100 screw-in resistance thermometers for bearings	FS 180 ~ 355
K45	Anti-condensation heater for 220Vac (spaces heater)	FS 80 ~ 355
W04	Temperture class 155 (F), used acc. to 130 (B) with service factor 1.15	FS 80 ~ 315
Mechanical design		
K09 ¹⁾	Terminal box on RHS (view from drive end)	FS 80 ~ 355
K10 ¹⁾	Terminal box on LHS (view from drive end)	FS 80 ~ 355
K11 ¹⁾	Terminal box on top, cable entry on right (view from drive end)	FS 80 ~ 355
K83	Rotation of terminal box by 90°, inserted from drive end	FS 80 ~ 355
K84	Rotation of terminal box by 90°, inserted from non-drive end	FS 80 ~ 355
K85	Rotation of terminal box by 180°	FS 80 ~ 355
K16 ²⁾	Second standard shaft-extension	FS 80 ~ 355
K40	Regreasing device	FS 180 ~ 280
W01	SKF bearings	FS 80 ~ 355
W02	NSK bearings	FS 80 ~ 355
W03	Motor shaft DE equipped with Oil seal	FS 80 ~ 132
Paint		
Y53	Finish in other colours - please specify RAL7032 or RAL9006	FS 80 ~ 355
Testing certificate		
B02	Acceptance test certificate 3.1 according to EN 10204	FS 80 ~ 355

¹⁾ Indication of terminal box position is not necessary for motor with flange. For motor with K10, the connection box is close to NDE.

²⁾ Motor without feet and with flange on the end-shield (DE), and with canopy on non-driven end should not be associated with this option.

Technical data

Table 1

Frame Size	Type	Rated Output	Rated speed	Efficiency at (50Hz) 4 / 4 load	Efficiency at (50Hz) 3 / 4 load	Power factor	Rated current	Rated torque
		P_{rated}	n_{rated}	η_{rated}	η_{rated}	$\cos \phi_{rated}$	I_{rated}	T_{rated}
		kW	rpm	%	%		A	Nm
3000rpm 2-pole								
220VD / 380VY 50Hz								
80M	1LG0 080-2AA..	0.75	2845	76	75.1	0.83	1.81	2.5
80M	1LG0 083-2AA..	1.1	2840	77.4	80	0.84	2.57	3.7
90S	1LG0 090-2AA..	1.5	2840	79	79.2	0.84	3.43	5
90L	1LG0 096-2AA..	2.2	2840	81.1	81.8	0.85	4.85	7.4
100L	1LG0 106-2AA..	3	2860	83	83.2	0.88	6.31	10
380VD / 660VY 50Hz								
112M	1LG0 113-2AA..	4	2880	85	85.8	0.88	8.1	13.3
132S	1LG0 130-2AA..	5.5	2900	86	87.1	0.88	11	18.1
132S	1LG0 131-2AA..	7.5	2900	87	88.7	0.88	14.9	24.7
160M	1LG0 163-2AA..	11	2930	88.4	88.6	0.89	21.2	35.9
160M	1LG0 164-2AA..	15	2930	89.4	90	0.89	28.6	48.9
160L	1LG0 166-2AA..	18.5	2930	91	91	0.9	34.3	60.3
180M	1LG0 183-2AA..	22	2940	91.2	90.2	0.89	41.2	71.5
200L	1LG0 206-2AA..	30	2950	91.4	91.2	0.9	55.4	97.1
200L	1LG0 207-2AA..	37	2950	92	92.2	0.9	67.9	120
225M	1LG0 223-2AA..	45	2960	92.5	92.6	0.9	82.1	145
250M	1LG0 253-2AB..	55	2965	93	92.8	0.9	100	177
280S	1LG0 280-2AB..	75	2970	93.6	93	0.9	135	241
280M	1LG0 283-2AB..	90	2970	93.9	93.7	0.91	160	289
315S	1LG0 310-2AC..	110	2975	94	93.2	0.91	195	353
315M	1LG0 313-2AC..	132	2975	94.5	93.9	0.91	233	424
315L	1LG0 316-2AC..	160	2975	94.6	94	0.92	279	514
315L	1LG0 317-2AC..	200	2975	94.8	94.9	0.92	348	642
355M	1LG0 353-2AC..	220	2987	94.8	94.8	0.92	383	703
355M	1LG0 354-2AC..	250	2987	95.2	94.9	0.9	444	799
355L	1LG0 356-2AC..	280	2987	95.2	95.1	0.9	497	895
355L	1LG0 357-2AC..	315	2987	95.4	95.4	0.9	558	1007

Penultimate position:					
Voltage Identifier No.					
220VD / 380VY 50Hz	380VD / 660VY 50Hz	230VD / 400VY 50Hz	400VD / 690VY 50Hz	E-Voltage / Frequency	
2	7	1	6	9	

Rated Output	Rated speed	Efficiency	Power factor	Rated current	Rated torque	Starting current	Starting torque	Max torque	Moment of inertia J	Weight
P_{rated}	n_{rated}	η_{rated}	$\cos \phi_{rated}$	I_{rated}	T_{rated}	I_{LR} / I_{rated}	T_{LR} / T_{rated}	T_B / T_{rated}		
kW	rpm	%		A	Nm				kgm ²	kg
440VY 60Hz										
0.86	3450	76.0	0.83	1.79	2.38	6.1	2.3	2.7	0.0008	14
1.3	3430	79.0	0.84	2.57	3.62	7	2.3	2.5	0.0009	15
1.75	3440	80.0	0.84	3.42	4.86	6.9	2.3	2.3	0.0012	22
2.55	3440	82.0	0.85	4.80	7.08	6.9	2.3	2.8	0.0014	24
3.45	3460	84.0	0.87	6.19	9.52	6.9	2.3	2.8	0.0039	33
440VD 60Hz										
4.6	3480	86.0	0.88	8.0	12.6	7.2	2.3	2.8	0.0055	38
6.3	3500	86.0	0.88	10.9	17.2	7.5	2.3	2.8	0.0109	58
8.6	3500	87.0	0.88	14.7	23.5	7.4	2.3	2.8	0.013	63
12.6	3520	89.5	0.89	20.8	34.2	7.5	2.5	2.6	0.038	105
17.3	3520	90.0	0.895	28.2	46.9	7.3	2.5	2.9	0.045	115
21.3	3520	90.5	0.905	34.1	57.8	7.2	2.5	2.8	0.055	128
24.5	3540	90.0	0.90	39.7	66.1	7.5	2.3	2.9	0.075	165
33.5	3540	91.2	0.90	53.6	90.4	6.9	2.2	2.9	0.124	225
41.5	3540	92.0	0.90	65.8	112	7.1	2.3	2.9	0.139	246
51	3550	92.8	0.91	79.2	137	7.3	2.5	2.9	0.233	296
62	3560	92.5	0.90	98	166	7.5	2.5	2.9	0.312	390
84	3560	93.0	0.90	132	225	7.5	2.3	2.9	0.597	504
101	3560	93.8	0.91	155	271	7.5	2	2.3	0.675	536
123	3570	94.0	0.91	189	329	7.1	1.8	2.2	1.18	865
148	3570	94.5	0.91	226	396	7.1	1.8	2.2	1.55	960
180	3570	94.6	0.92	271	482	7	1.9	2.5	1.76	1035
224	3570	94.8	0.92	337	599	7.1	1.8	2.2	2.02	1160
246	3580	94.8	0.92	370	656	7.1	1.4	2.2	3.02	1545
280	3580	95.3	0.92	419	747	7.1	1.4	2.2	3.56	1650
314	3580	95.3	0.92	470	838	7.1	1.4	2.2	3.84	1650
353	3580	95.6	0.92	527	942	7.1	1.4	2.2	4.16	1790

Final position			
Type of construction Identifier No.			
With feet and without flange on the end-shield	Without feet and with flange on the end-shield	With feet and with flange on the end-shield	Without feet and with flange on the end-shield, and with Canopy on non-driven end
0	1 8 ¹⁾	6	4

¹⁾ Code "8" is only for FS 250 ~ 355 1LGO motor with mounting type "IMV1 without canopy"; for FS 80 ~ 225 1LGO motor with mounting type "IMV1 without canopy", the 12th position is "1".

Technical data

Table 2

Frame Size	Type	Rated Output	Rated speed	Efficiency at (50Hz) 4 / 4 load	Efficiency at (50Hz) 3 / 4 load	Power factor	Rated current	Rated torque
		P_{rated}	n_{rated}	η_{rated}	η_{rated}	$\cos \phi_{rated}$	I_{rated}	T_{rated}
		kW	rpm	%	%		A	Nm
1500rpm 4-pole								
220VD / 380VY 50Hz								
80M	1LG0 080-4AA..	0.55	1390	71	71.9	0.75	1.57	3.8
80M	1LG0 083-4AA..	0.75	1380	73	74.7	0.76	2.05	5.2
90S	1LG0 090-4AA..	1.1	1390	76.2	75	0.76	2.89	7.6
90L	1LG0 096-4AA..	1.5	1390	78.5	75.8	0.79	3.67	10.3
100L	1LG0 106-4AA..	2.2	1410	81	78.8	0.8	5.16	14.9
100L	1LG0 107-4AA..	3	1410	82.8	80.9	0.81	6.8	20.3
380VD / 660VY 50Hz								
112M	1LG0 113-4AA..	4	1435	84.5	84	0.82	8.8	26.6
132S	1LG0 130-4AA..	5.5	1440	86	85.9	0.82	11.8	36.5
132M	1LG0 133-4AA..	7.5	1440	87.2	87.4	0.84	15.6	49.7
160M	1LG0 163-4AA..	11	1460	89	88.5	0.83	22.6	72
160L	1LG0 166-4AA..	15	1460	90	89.7	0.84	30.1	98.1
180M	1LG0 183-4AA..	18.5	1470	90.6	91.2	0.86	36.1	120.2
180L	1LG0 186-4AA..	22	1470	91.4	91.6	0.86	42.5	143
200L	1LG0 206-4AA..	30	1470	92.1	92.3	0.86	57.5	195
225S	1LG0 220-4AA..	37	1475	92.6	92.7	0.87	69.8	240
225M	1LG0 223-4AA..	45	1475	92.8	93.2	0.87	84.7	291
250M	1LG0 253-4AA..	55	1480	93	93.3	0.87	103	355
280S	1LG0 280-4AA..	75	1480	93.8	93.6	0.87	140	484
280M	1LG0 283-4AA..	90	1480	94.3	94.1	0.87	167	580
315S	1LG0 310-4AB..	110	1480	94.6	94	0.88	201	710
315M	1LG0 313-4AB..	132	1480	94.9	94.4	0.88	240	852
315L	1LG0 316-4AB..	160	1480	95.1	94.8	0.89	287	1032
315L	1LG0 317-4AB..	200	1480	95.3	94.9	0.89	358	1291
355M	1LG0 353-4AB..	220	1490	95	95.3	0.89	395	1410
355M	1LG0 354-4AB..	250	1490	95.2	95.3	0.87	459	1602
355L	1LG0 356-4AB..	280	1490	95.2	95.4	0.87	514	1794
355L	1LG0 357-4AB..	315	1490	95.2	95.4	0.87	578	2019

Penultimate position:				
Voltage Identifier No.				
220VD / 380VY 50Hz	380VD / 660VY 50Hz	230VD / 400VY 50Hz	400VD / 690VY 50Hz	E-Voltage / Frequency
2	7	1	6	9

Rated Output	Rated speed	Efficiency	Power factor	Rated current	Rated torque	Starting current	Starting torque	Max torque	Moment of inertia J	Weight
P_{rated}	n_{rated}	η_{rated}	$\cos \phi_{rated}$	I_{rated}	T_{rated}	I_{LR} / I_{rated}	T_{LR} / T_{rated}	T_B / T_{rated}		
kW	rpm	%		A	Nm				kgm ²	kg
440VY 60Hz										
0.63	1690	73.0	0.75	1.51	3.56	5	2.4	2.6	0.002	14
0.86	1680	75.0	0.76	1.98	4.89	5.8	2.4	2.6	0.002	15
1.3	1680	77.0	0.77	2.88	7.39	5.8	2.3	2.5	0.0021	21
1.75	1680	79.0	0.79	3.68	9.95	5.8	2.4	2.8	0.003	23
2.55	1710	81.0	0.81	5.10	14.2	6	2.4	2.3	0.007	31
3.45	1710	83.0	0.82	6.65	19.3	6	2.3	2.8	0.007	33
440VD 60Hz										
4.6	1730	85.0	0.82	8.7	25.4	6.2	2.3	2.8	0.0095	44
6.3	1740	85.5	0.85	11.4	34.6	6.5	2.3	2.8	0.0214	61
8.6	1740	87.0	0.84	15.4	47.2	7	2.5	2.8	0.0296	71
12.6	1750	89.0	0.85	21.9	68.8	7	2.4	2.9	0.075	110
17.3	1750	89.5	0.85	29.8	94.4	7.5	2.5	2.9	0.092	132
21.3	1760	91.0	0.86	35.7	116	7	2.3	2.9	0.139	164
24.5	1760	91.5	0.865	40.6	133	7	2.4	2.9	0.158	180
33.5	1760	92.5	0.86	55.3	182	7	2.3	2.8	0.262	225
41.5	1770	92.8	0.87	67.4	224	6.9	2.2	2.7	0.406	285
51	1770	93.0	0.87	82.7	275	6.9	2.2	2.3	0.469	305
62	1770	93.5	0.875	99	335	7.1	2.4	2.8	0.66	400
84	1780	93.8	0.88	134	451	6.8	2.3	2.8	1.12	553
101	1780	94.3	0.88	160	542	7.2	2.4	2.8	1.46	582
123	1780	94.5	0.88	194	660	6.2	2.3	2.8	3.11	900
148	1780	94.8	0.88	233	794	6.1	2.2	2.8	3.29	995
180	1780	94.9	0.89	280	966	6.5	2.2	2.8	3.79	1070
224	1780	95.0	0.89	348	1202	6.4	2.1	2.8	4.49	1220
246	1780	95.0	0.89	382	1320	6.9	1.6	2.2	4.82	1645
280	1780	95.3	0.90	428	1502	6.9	1.6	2.2	5.67	1685
314	1780	95.3	0.90	480	1685	6.9	1.6	2.2	6.13	1780
353	1780	95.6	0.90	538	1894	6.9	1.6	2.2	6.66	1890

Final position					
Type of construction Identifier No.					
With feet and without flange on the end-shield		Without feet and with flange on the end-shield		With feet and with flange on the end-shield	Without feet and with flange on the end-shield, and with Canopy on non-driven end
0		1 8 ¹⁾		6	4

¹⁾ Code "8" is only for FS 250 ~ 355 1LG0 motor with mounting type "IMV1 without canopy"; for FS 80 ~ 225 1LG0 motor with mounting type "IMV1 without canopy", the 12th position is "1".

Technical data

Table 3

Frame Size	Type	Rated Output	Rated speed	Efficiency at (50Hz) 4 / 4 load	Efficiency at (50Hz) 3 / 4 load	Power factor	Rated current	Rated torque
		P_{rated}	n_{rated}	η_{rated}	η_{rated}	$\cos \phi_{rated}$	I_{rated}	T_{rated}
		kW	rpm	%	%		A	Nm
1000rpm 6-pole								
220VD / 380VY 50Hz								
80M	1LG0 083-6AA..	0.55	885	65	67.3	0.72	1.79	5.9
90S	1LG0 090-6AA..	0.75	910	69	70.2	0.72	2.29	7.9
90L	1LG0 096-6AA..	1.1	910	72	74.5	0.73	3.18	11.5
100L	1LG0 106-6AA..	1.5	920	76	78.2	0.75	4	15.6
112M	1LG0 113-6AA..	2.2	935	80	81.3	0.75	5.6	22.5
132S	1LG0 130-6AA..	3	960	81.5	82.2	0.76	7.4	29.8
380VD / 660VY 50Hz								
132M	1LG0 133-6AA..	4	960	82	83.9	0.76	9.8	38.2
132M	1LG0 134-6AA..	5.5	960	84.4	86.3	0.77	12.9	52.5
160M	1LG0 163-6AA..	7.5	970	86	87.9	0.77	17.2	71.6
160L	1LG0 166-6AA..	11	970	87.5	89.1	0.78	24.5	105.1
180L	1LG0 186-6AA..	15	970	89	89.6	0.83	30.9	143
200L	1LG0 206-6AB..	18.5	980	90	90.1	0.81	38.6	177
200L	1LG0 207-6AB..	22	980	90	91.1	0.83	44.7	210
225M	1LG0 223-6AB..	30	980	91.7	92.3	0.84	59.2	287
250M	1LG0 253-6AB..	37	980	92	92.1	0.86	71	353
280S	1LG0 280-6AB..	45	980	92.5	92.6	0.86	86	430
280M	1LG0 283-6AB..	55	980	92.8	93.2	0.86	105	525
315S	1LG0 310-6AB..	75	989	93.5	93.8	0.86	142	724
315M	1LG0 313-6AB..	90	989	93.8	94.1	0.86	170	869
315L	1LG0 316-6AB..	110	989	94.3	94.5	0.86	206	1062
315L	1LG0 317-6AB..	132	989	94.6	94.8	0.87	244	1274
355M	1LG0 353-6AB..	160	989	94.5	94.2	0.88	292	1609
355M	1LG0 354-6AB..	185	989	94.5	94.4	0.88	338	1861
355M	1LG0 355-6AB..	200	989	94.7	94.6	0.88	365	2012
355L	1LG0 356-6AB..	220	989	94.7	94.7	0.88	401	2213

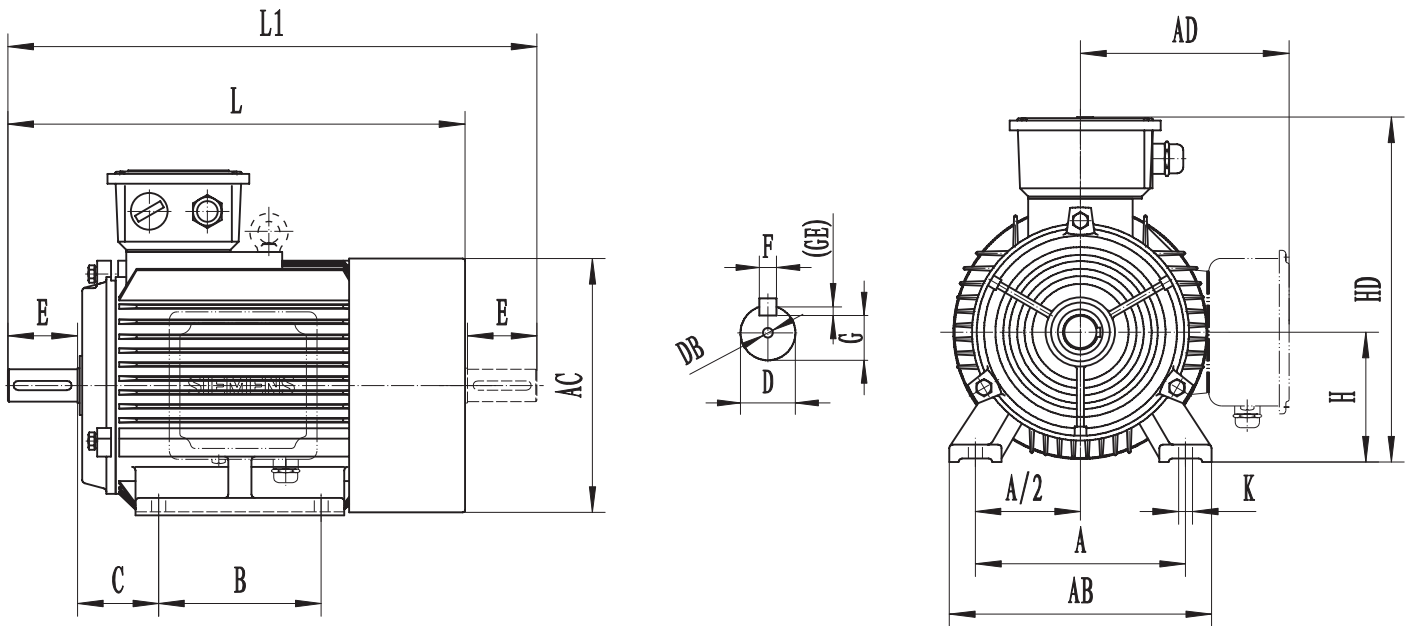
Penultimate position:				
Voltage Identifier No.				
220VD / 380VY 50Hz	380VD / 660VY 50Hz	230VD / 400VY 50Hz	400VD / 690VY 50Hz	E-Voltage / Frequency
2	7	1	6	9

Rated Output	Rated speed	Efficiency	Power factor	Rated current	Rated torque	Starting current	Starting torque	Max torque	Moment of inertia J	Weight
P_{rated}	n_{rated}	η_{rated}	$\cos \phi_{rated}$	I_{rated}	T_{rated}	I_{LR} / I_{rated}	T_{LR} / T_{rated}	T_B / T_{rated}		
kW	rpm	%		A	Nm				kgm ²	kg
440VY 60Hz										
0.63	1080	66.0	0.72	1.74	5.57	4.7	1.9	2.1	0.003	16
0.86	1100	71.0	0.72	2.21	7.47	5	2	2.3	0.0029	20
1.3	1100	73.5	0.73	3.18	11.3	5	2.1	2.3	0.0035	23
1.75	1110	78.0	0.75	3.93	15.1	5	2.2	2.4	0.0069	31
2.55	1130	81.0	0.76	5.4	21.6	5	2.4	2.4	0.0138	40
3.45	1160	82.0	0.76	7.3	28.4	6	2.1	2.6	0.0286	56
440VD 60Hz										
4.6	1160	83.0	0.76	9.6	37.9	6	2.1	2.8	0.036	68
6.3	1160	86.0	0.77	12.5	51.9	6.4	2.1	2.8	0.045	75
8.6	1160	87.5	0.78	16.5	70.8	6.5	2	2.7	0.088	104
12.6	1160	88.5	0.78	24.0	104	6.5	2	2.9	0.116	127
17.3	1170	90.0	0.82	30.8	141	6.5	2.2	2.7	0.207	167
21.3	1170	90.5	0.82	37.7	174	6.5	2.2	2.8	0.315	210
24.5	1170	91.0	0.835	42.3	200	6.5	2.1	2.6	0.36	223
33.5	1170	92.0	0.85	56.2	273	6.5	2	2.6	0.547	290
41.5	1170	92.0	0.87	68	339	6.9	2.1	2.8	0.834	375
51	1180	92.5	0.86	84	413	7	2.2	2.8	1.39	492
62	1180	93.0	0.865	101	502	7	2.1	2	1.65	530
84	1186	93.8	0.86	137	676	7	2.3	2.8	4.11	820
101	1186	93.8	0.86	164	813	6.2	2	2.7	4.28	895
123	1186	94.0	0.86	200	990	6.2	2	2.6	5.45	1010
148	1186	94.5	0.87	236	1192	6.5	2	2.8	6.12	1080
180	1180	94.5	0.88	284	1457	6.7	1.9	2	8.85	1590
207	1180	94.5	0.88	327	1675	6.7	1.9	2	8.98	1660
224	1180	94.7	0.88	353	1813	6.7	1.9	2	9.55	1730
246	1180	94.7	0.88	387	1991	6.7	1.9	2	10.09	1835

Final position			
Type of construction Identifier No.			
With feet and without flange on the end-shield	Without feet and with flange on the end-shield	With feet and with flange on the end-shield	Without feet and with flange on the end-shield, and with Canopy on non-driven end
0	1 8 ¹⁾	6	4

¹⁾ Code "8" is only for FS 250 ~ 355 1LGO motor with mounting type "IMV1 without canopy"; for FS 80 ~ 225 1LGO motor with mounting type "IMV1 without canopy", the 12th position is "1".

Dimension drawings



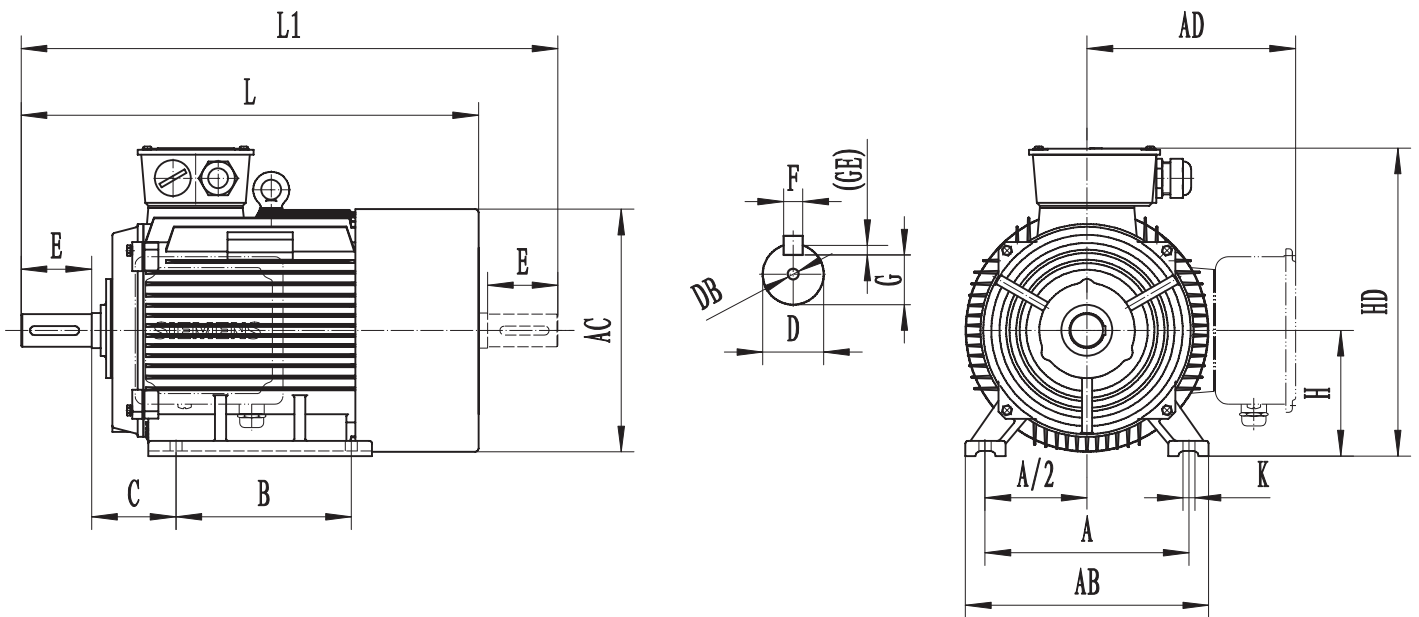
FS 80 ~ 132 (1LG0080...1LG0134)
 Note: FS 80 ~ 90 motor without eyebolts

Table 1 Frame with feet and without flange on the end shield

Frame size		Poles	Mounting Dimensions and Tolerance										
			A	A/2	B	C		D		E		F	
80M	1LG0080...1LG0083	2, 4, 6	125	62.5	100	50	±1.5	19	+0.009 -0.004	40	±0.310	6	0 -0.030
90S	1LG0090		140	70	100	56		24		50		8	0 -0.036
90L	1LG0096				125		28	60					
100L	1LG0106...1LG0107		160	80	140	63	±2.0	28	60	10			
112M	1LG0113		190	95	140	70		38	80				
132S	1LG0130...1LG0131		216	108	140	89	±3.0	42	+0.018 +0.002	110	±0.430	12	0 -0.043
132M	1LG0133...1LG0134				178							48	
160M	1LG0163...1LG0164		254	127	210	108						55	
160L	1LG0166		254	121	16								
180M	1LG0183		279	139.5	241	121	±4.0	60	+0.030 +0.011	140	±0.500	14	18
180L	1LG0186				279							55	
200L	1LG0206...1LG0207		318	159	305	133						65	
225S	1LG0220	4	356	178	311	149	60	+0.030 +0.011	140	±0.500	18	18	
225M	1LG0223	2					55		110		16		
		4, 6					60		140				
250M	1LG0253	2	406	203	349	168	65	140	±0.500	18			
		4, 6											

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($\begin{matrix} +0.10 \\ 0 \end{matrix}$), for other frame size ($\begin{matrix} +0.20 \\ 0 \end{matrix}$).

²⁾ K hole's positional tolerance is based on the central line of shaft extension.

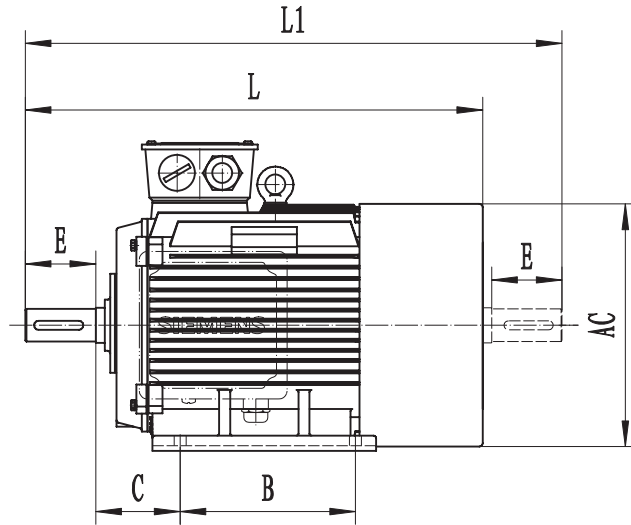


FS 160 ~ 250 (1LG0163...1LG0253)

mm

					Contour Dimensions											
G ¹⁾		H		K ²⁾		DB	AB	AC	AD	HD	L	L1				
15.5	0 -0.10	80	0 -0.5	10	+0.360 0	φ 1.0 (M)	M6	165	164	145	220	295	335			
20	0 -0.20	90					12	+0.430 0	φ 1.5 (M)	M8	180	184	155	250	320	375
24		100		19	+0.520 0	φ 2.0 (M)				M10	205	204	180	270	345	400
		112								M12	270	267	210	300	385	445
33		132		15	+0.520 0	φ 2.0 (M)				M16	230	228	190	300	400	465
37		160					24	+0.520 0	φ 2.0 (M)		M20	470	467	210	345	470
		180		320	325	255				420		615	735			
42.5		200		19	+0.520 0	φ 2.0 (M)	M20	665	662	255	420	665	779			
49		225						355	366	280	455	700	810			
49	250	24		+0.520 0	φ 2.0 (M)	M20	395	408	305	505	770	880				
53			435				456	335	560	815	965					
53	250	24	+0.520 0	φ 2.0 (M)	M20	820	827	335	560	820	935					
58						490	504	370	615	915	1060					
											1060	1060				

Dimension drawings



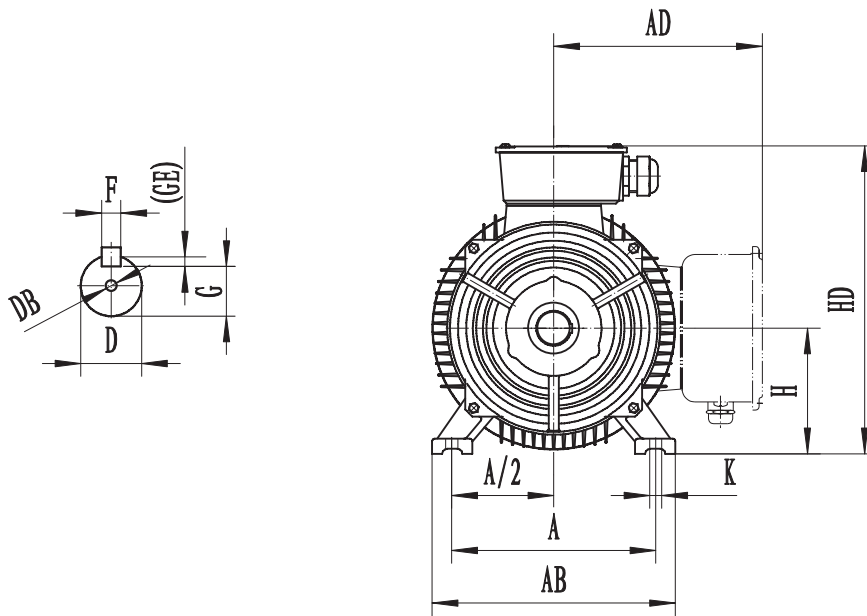
FS 280 ~ 355 (1LG0280...1LG0357)

Table 1 (Continuous) Frame with feet and without flange on the end shield

Frame size		Poles	Mounting Dimensions and Tolerance											
			A	A/2	B	C	D		E	F				
280S	1LG0280	2	457	228.5	368	190	±4.0	65	+0.030 +0.011	140	±0.500	18	0 -0.043	
		4, 6			75			20				0 -0.052		
280M	1LG0283	2			419			216				65	18	0 -0.043
		4, 6			75							20	0 -0.052	
315S	1LG0310	2	508	254	406	±4.0	65	+0.030 +0.011	170	±0.500	18	0 -0.043		
		4, 6			80		22				0 -0.052			
315M	1LG0313	2			457		254				65	140	18	0 -0.043
		4, 6			80						170	22	0 -0.052	
315L	1LG0316...1LG0317	2	610	305	508	±4.0	65	+0.035 +0.013	170	±0.500	18	0 -0.043		
		4, 6			80		170				22	0 -0.052		
355M	1LG0353...1LG0355	2			560		254				75		140	20
		4, 6			95						170	25		
355L	1LG0356...1LG0357	2	630	305	630	±4.0	75	+0.030 +0.011	140	±0.500	20	0 -0.052		
		4, 6			95		170				25			

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($+0.10$), for other frame size ($+0.20$).

²⁾ K hole's positional tolerance is based on the central line of shaft extension. 0

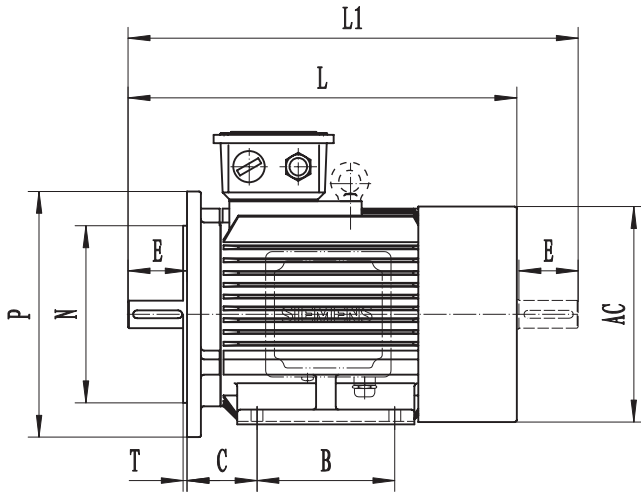


FS 280 ~ 355 (1LG0280...1LG0357)

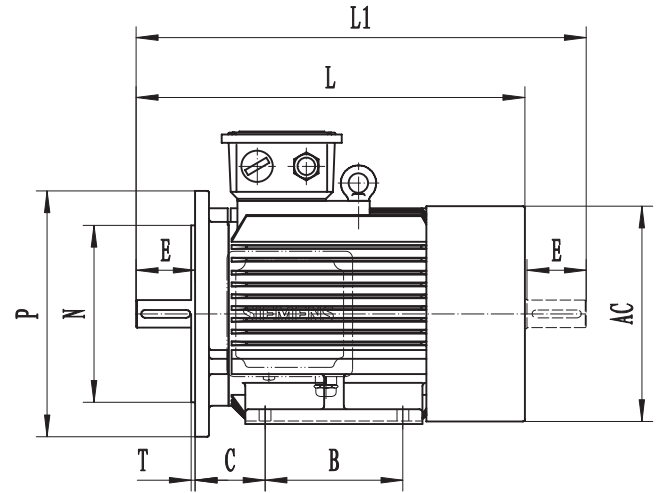
mm

								Contour Dimensions					
G ¹⁾		H		K ²⁾		DB	AB	AC	AD	HD	L	L1	
58	0 -0.20	280	0	24	+0.520 0	φ 2.0 (M)	M20	550	566	410	680	960	1105
67.5												980	1125
58												1010	1156
67.5												1030	1176
58		315	-1.0	28				635	639	530	845	1190	1330
71												1220	1390
58												1300	1440
71												1330	1500
58		355			730	718	655	1010	1300	1440			
71									1330	1500			
67.5									1500	1640			
86									1530	1700			
67.5					M24				1500	1640			
86					M20				1530	1700			
					M24				1500	1640			
					M24				1530	1700			

Dimension drawings



FS 80 ~ 132 (1LG0080...1LG0134)
Note: FS 80 ~ 90 motor without eyebolts



FS 160 ~ 250 (1LG0163...1LG0253)

Table 2 Frame with feet and with flange (with through holes) on the end shield

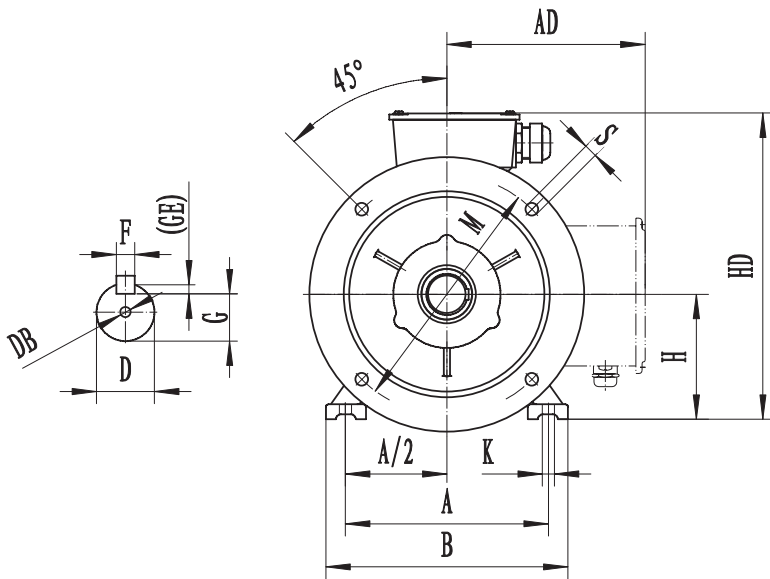
Frame size		Flang number	Poles	Mounting Dimensions and Tolerance														
				A	A/2	B	C	D	E	F	G ¹⁾		H					
80M	1LG0080...1LG0083	FF165	2, 4, 6	125	62.5	100	50	±1.5	19	+0.009 -0.004	40	±0.310	6	0 -0.030	15.5	0 -0.10	80	0 -0.5
90S	1LG0090			140	70	100	56		24		50		8	20	90			
90L	1LG0096			125	56	24	50	8	20		90							
100L	1LG0106...1LG0107	FF215		160	80	140	63	±2.0	28	±0.370	60	0 -0.036	24	100				
112M	1LG0113			190	95	140	70		38		80		10	33	132			
132S	1LG0130...1LG0131	FF265		216	108	140 178	89	38	80		10	33	132					
132M	1LG0133...1LG0134	FF300		254	127	210 254	108	±3.0	42	+0.018 +0.002	110	±0.430	12	0 -0.20	37	160		
160M	1LG0163...1LG0164			279	139.5	241 279	121		48				14		42.5	180		
160L	1LG0166			279	139.5	241 279	121		48	14		42.5	180					
180M	1LG0183			FF350	318	159	305	133	±4.0	55		+0.030 +0.011	140	±0.500	16	0 -0.043	49	
200L	1LG0206...1LG0207		318		159	305	133	55		16					49		200	
225S	1LG0220	FF400	2	356	178	311	149	60	+0.030 +0.011	110	±0.430		16	0 -0.043	53	225		
225M	1LG0223		4, 6					60					140		±0.500		18	53
250M	1LG0253		2					406		203	349		168	65	140	±0.500	18	58
		4, 6	406	203	349	168	65	140		±0.500	18	58	250					

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($+0.10$ / 0), for other frame size ($+0.20$ / 0).

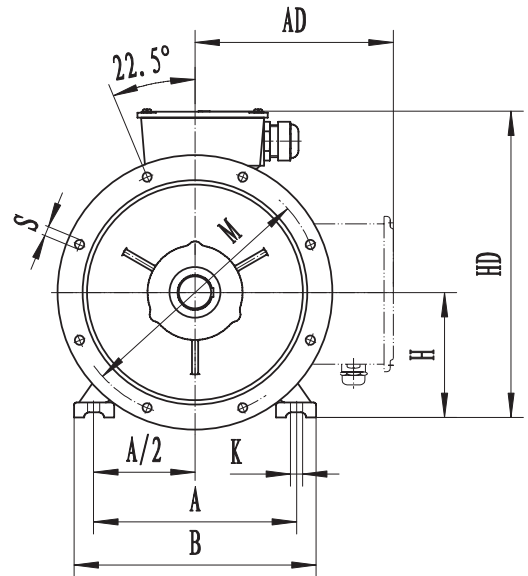
²⁾ K hole's positional tolerance is based on the central line of shaft extension

³⁾ Dimension of P is the maximum limit

⁴⁾ R is the distance from the flange the flange to the drive shaft end.



FS 80 ~ 200 (1LG0080...1LG0207)

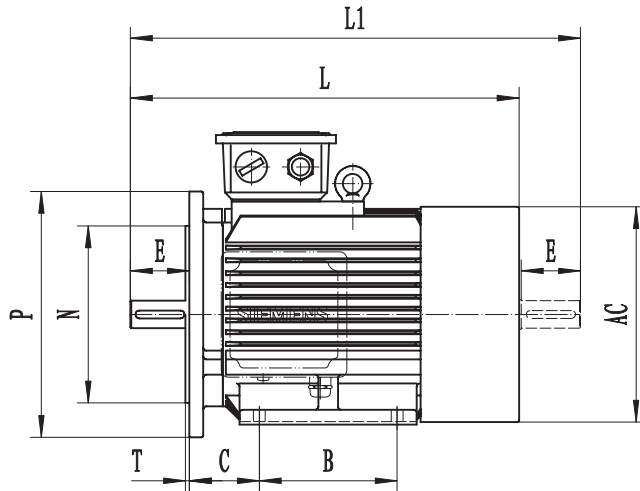


FS 225 ~ 250 (1LG0220...1LG0253)

mm

											Contour Dimensions								
K ²⁾		M	N		P ³⁾	R ⁴⁾		S ²⁾		T	Flange hole number	DB	AB	AC	AD	HD	L	L1	
10	+0.360 0	165	130	+0.014 -0.011	200	±1.5	12	+0.430 0	φ 1.0 (M)	3.5	4	M6	165	164	145	220	295	335	
												M8	180	184	155	250	320	375	
12	+0.430 0	215	180	250	±2.0	15	0	φ 1.5 (M)	4	M10		205	204	180	270	385	445		
										M12		230	228	190	300	400	465		
15	+0.430 0	265	230	300	0	±3.0	19	+0.520 0	φ 1.5 (M)	5		M16	270	267	210	345	470	555	
												M16	320	325	255	420	615	735	
19	+0.520 0	300	250	+0.016 -0.013	350	±3.0	19	+0.520 0	φ 1.5 (M)	5		M16	355	366	280	455	700	810	
												M16	355	366	280	455	730	848	
19	+0.520 0	350	300	±0.016	400	±4.0	19	+0.520 0	φ 1.5 (M)	5		8	M20	395	408	305	505	770	880
													M20	435	456	335	560	815	965
24	+0.520 0	400	350	±0.018	450	±4.0	19	+0.520 0	φ 1.5 (M)	5			M20	490	504	370	615	820	935
													M20	490	504	370	615	845	990
24	+0.520 0	500	450	±0.020	550	±4.0	19	+0.520 0	φ 1.5 (M)	5	M20		490	504	370	615	915	1060	
											M20		490	504	370	615	915	1060	

Dimension drawings



FS 280 ~ 355 (1LG0280...1LG0357)

Table 2 (Continuous) Frame with feet and with flange (with through holes) on the end shield

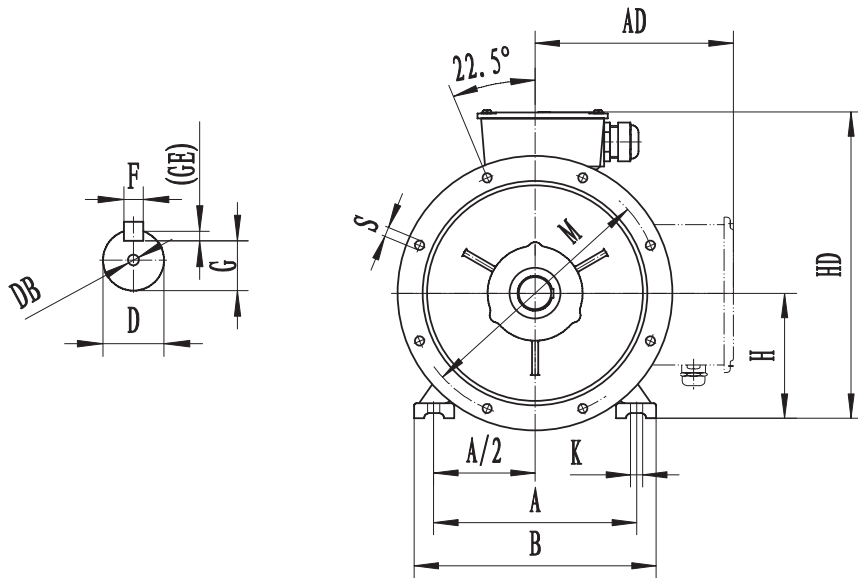
Frame size		Flang number	Poles	Mounting Dimensions and Tolerance															
				A	A/2	B	C	D		E	F		G ¹⁾	H					
280S	1LG0280	F500	2	457	228.5	368	190	±4.0	65	140	±0.500	18	0 -0.043	58	280				
			4, 6						75			20	0 -0.052	67.5					
280M	1LG0283		2						419			65	18	0 -0.043			58		
			4, 6									75	20	0 -0.052			67.5		
315S	1LG0310	FF600	2	508	254	406	216	±4.0	65	170	±0.500	18	0 -0.043	58	315	0 -1.0			
			4, 6						80			22	0 -0.052	71					
315M	1LG0313		2						457			65	18	0 -0.043			58		
			4, 6									80	22	0 -0.052			71		
315L	1LG0316...1LG0317		2						508			508	65	140			18	0 -0.043	58
			4, 6										80	170			22	0 -0.052	71
355M	1LG0353...1LG0355	2	610	305	560	254	±4.0	75	170	±0.500	20	0 -0.052	67.5	355					
		4, 6						95			25	86							
355L	1LG0356...1LG0357	2	630	630	630	254	±4.0	75	140	±0.500	20	0 -0.052	67.5	355					
		4, 6						95			25	86							

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($\begin{matrix} +0.10 \\ 0 \end{matrix}$), for other frame size ($\begin{matrix} +0.20 \\ 0 \end{matrix}$).

²⁾ K hole's positional tolerance is based on the central line of shaft extension

³⁾ Dimension of P is the maximum limit

⁴⁾ R is the distance from the flange the flange to the drive shaft end.

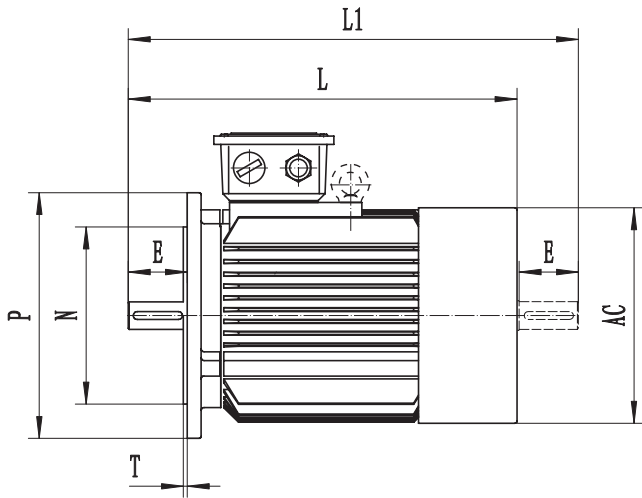


FS 280 ~ 355 (1LG0280...1LG0357)

mm

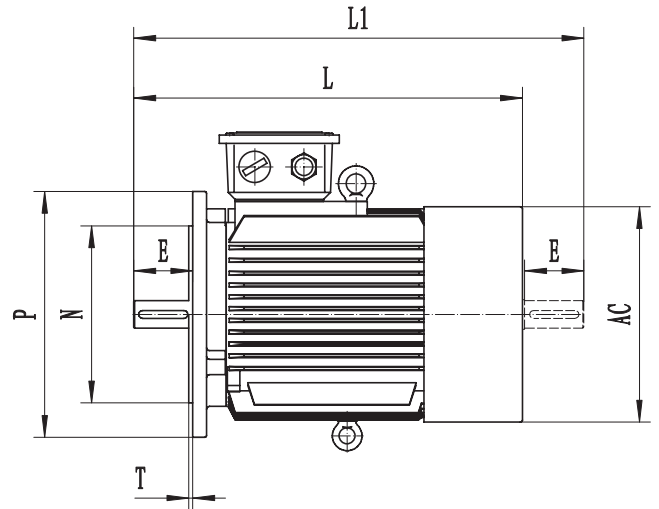
										Contour Dimensions										
K ²⁾		M	N		P ³⁾	R ⁴⁾		S ²⁾		T	Flange hole number	DB	AB	AC	AD	HD	L	L1		
24		500	450	0.020	550		19		φ 1.5 (M)	5	0 -0.120		550	566	410	680	960	1105		
																	980	1125		
																	1010	1156		
																	1030	1176		
28	+0.520 0	φ 2.0 (M)	600	550	±0.022	660	0	±4.0	+0.520 0		6	0 -0.150	8	635	639	530	845	1190	1330	
																		1220	1390	
																		1300	1440	
																		1330	1500	
			740	680	±0.025	800			24		φ 2.0 (M)	6	0 -0.150	8	635	718	655	1010	1300	1440
																			1330	1500
																			1500	1640
																			M24	1530
M20	1500	1640																		
M24	1530	1700																		

Dimension drawings



FS 80 ~ 132 (1LG0080...1LG0134)

Note: FS 80 ~ 90 motor without eyebolts



FS 160 ~ 180 (1LG0163...1LG0186)

Table 3 Frame without feet and with flange (with through holes) on the end shield

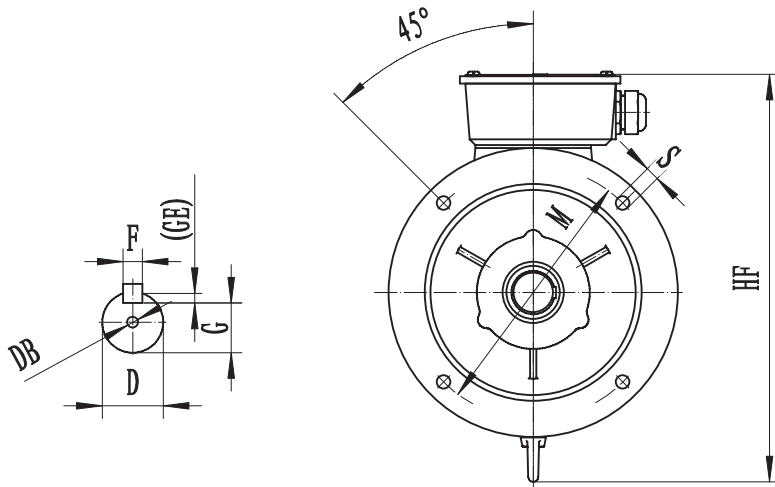
Frame size		Flang number	Poles	Mounting Dimensions and Tolerance							
				D		E		F		G ¹⁾	
80M	1LG0080...1LG0083	FF165	2, 4, 6	19	+0.009 -0.004	40	±0.310	6	0 -0.030	15.5	0 -0.10
90S	1LG0090			24		50		8	0 -0.036	20	
90L	1LG0096			28		60				24	
100L	1LG0106...1LG0107	FF215		38	+0.018 +0.002	80	±0.370	10	0 -0.043	33	0 -0.20
112M	1LG0113	FF265		42		110		12		37	
132S	1LG0130...1LG0131	FF300		48	+0.018 +0.002	110	±0.430	14	0 -0.043	42.5	
132M	1LG0133...1LG0134										
160M	1LG0163...1LG0164										
160L	1LG0166										
180M	1LG0183										
180L	1LG0186										

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($\begin{matrix} +0.10 \\ 0 \end{matrix}$), for other frame size ($\begin{matrix} +0.20 \\ 0 \end{matrix}$).

²⁾ S hole's positional tolerance is based on the central line of shaft extension

³⁾ Dimension of P is the maximum limit

⁴⁾ R is the distance from the flange to the drive shaft end.

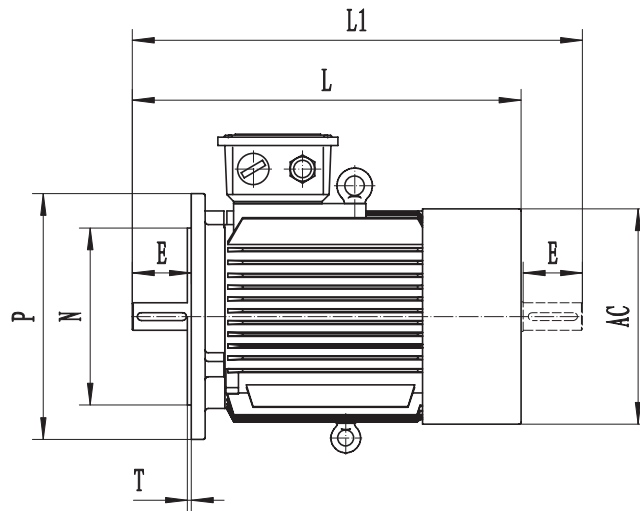


FS 80 ~ 180 (1LG0080...1LG0186)

mm

											Contour Dimensions					
M	N		P ³⁾	R ⁴⁾			S ²⁾		T		Flange hole number	DB	AC	HF	L	L1
165	130	+0.014 -0.011	200	0	±1.5	12	+0.430 0	φ 1.0 (M)	3.5	0 -0.120	4	M6	164	235	295	335
			215		180	250		±2.0	15			φ 1.5 (M)	4	M8	184	255
265	230	300		±3.0		19	+0.520 0			5				M10	204	290
		300	250		350			±3.0	19			+0.520 0	5	M12	228	315
300	250			+0.016 -0.013	350	±3.0	19			+0.520 0				5	5	M16
		300	250					+0.016 -0.013	350			±3.0	19			
300	250			+0.016 -0.013	350	±3.0	19			+0.520 0				5	5	M16
		300	250					+0.016 -0.013	350			±3.0	19			
300	250			+0.016 -0.013	350	±3.0	19			+0.520 0	5			5	M16	366

Dimension drawings



FS 200 ~ 280 (1LG0206...1LG0283)

Table 3 (Continuous) Frame without feet and with flange (with through holes) on the end shield

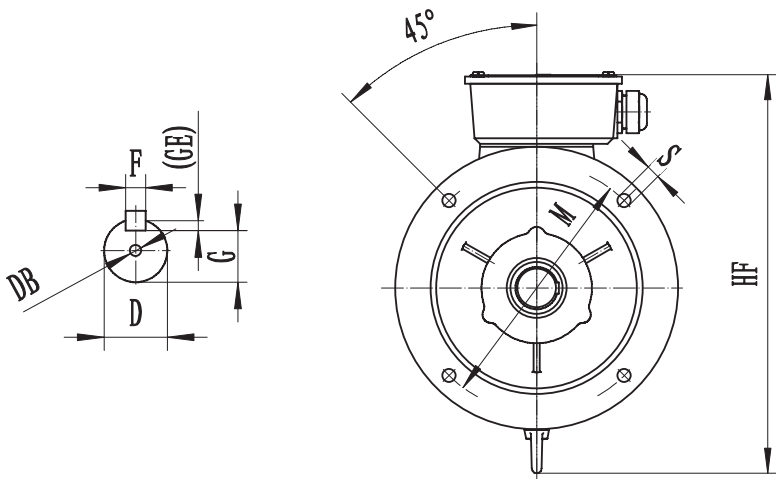
Frame size		Flang number	Poles	Mounting Dimensions and Tolerance							
				D		E		F		G ¹⁾	
200L	1LG0206...1LG0207	FF350	2, 4, 6	55	+0.030 +0.011	110	±0.430	16	0 -0.043	49	0 -0.20
225S	1LG0220		4	60		140	±0.500	18		53	
225M	1LG0223	2	55	110		±0.430	16	49			
		4, 6	60	140		±0.500	18	53			
250M	1LG0253	2	65					20	0 -0.052	67.5	
		4, 6	75	18		0 -0.043	58				
280S	1LG0280	FF500	4, 6				75	20	0 -0.052	67.5	
280M	1LG0283		2	65		18	0 -0.043			58	
			4, 6	75				20	0 -0.052	67.5	

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($\begin{matrix} +0.10 \\ 0 \end{matrix}$), for other frame size ($\begin{matrix} +0.20 \\ 0 \end{matrix}$).

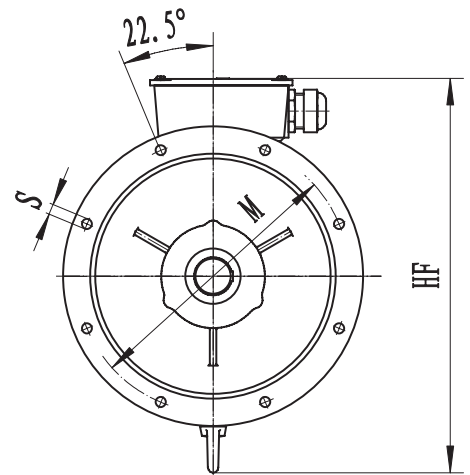
²⁾ S hole's positional tolerance is based on the central line of shaft extension

³⁾ Dimension of P is the maximum limit

⁴⁾ R is the distance from the flange to the drive shaft end.



FS 200 (1LG0206...1LG0207)

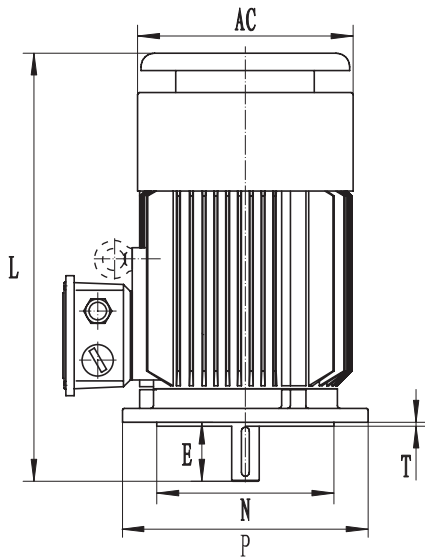


FS 225 ~ 280 (1LG0220...1LG0283)

mm

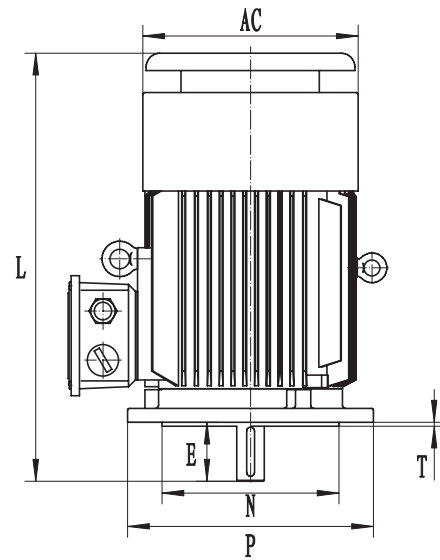
M	N		P ³⁾	R ⁴⁾		S ²⁾			T	Flange hole number	DB	Contour Dimensions				
												AC	HF	L	L1	
350	300	±0.016	400	±3.0						4	M20	408	570	770	880	
400	350	±0.018	450									4	456	615	815	965
															820	935
500	450	±0.020	550	0	±4.0	19	+0.520 0	φ 1.5 (M)	5	0 -0.120		8	504	685	915	1060
															1060	
															960	1105
											980				1125	
500	450	±0.020	550	0	±4.0	19	+0.520 0	φ 1.5 (M)	5	0 -0.120	8	566	760	1010	1156	
														1030	1176	

Dimension drawings



FS 80 ~ 132 (1LG0080...1LG0134)

Note: FS 80 ~ 90 motor without eyebolts



FS 160 ~ 250 (1LG0163...1LG0253)

Table 4 Vertically-mounted, Frame without feet and with flange (with through holes) on the end shield, shaft extension downwards

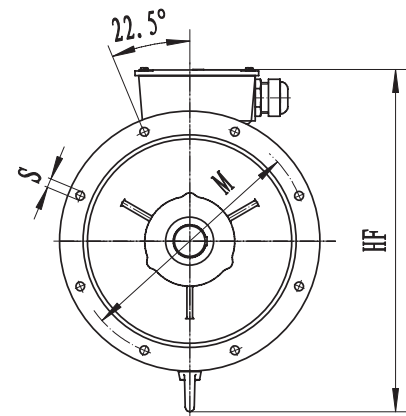
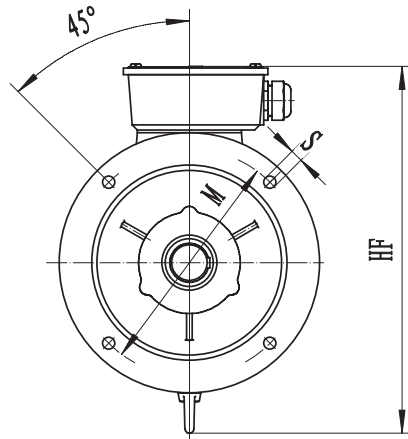
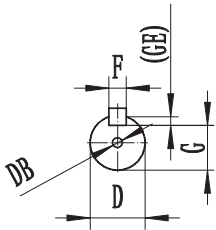
Frame size		Flang number	Poles	Mounting Dimensions and Tolerance									
				D		E		F		G ¹⁾			
80M	1LG0080...1LG0083	FF165	2, 4, 6	19	+0.009 -0.004	40	±0.310	6	0 -0.030	15.5	0 -0.10		
90S	1LG0090			24		50		8	0 -0.036	20			
90L	1LG0096			28		60				24			
100L	1LG0106...1LG0107	FF215		38	±0.370	80	10	33					
112M	1LG0113			42		+0.018 +0.002	110	12	37				
132S	1LG0130...1LG0131	FF265		48	±0.430		14	42.5					
132M	1LG0133...1LG0134			55			16	49					
160M	1LG0163...1LG0164	FF300		4	60	±0.500	18	0 -0.043	37				
160L	1LG0166								42	14	42.5		
180M	1LG0183								48	16	49		
180L	1LG0186	55	18						53				
200L	1LG0206...1LG0207	FF350	2						55	±0.430	16	0	49
225S	1LG0220												60
225M	1LG0223	FF400	4, 6						60	±0.500	18	0	49
250M	1LG0253												2
		FF500	4, 6						65	±0.500	18	0	58

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($+0.10$), for other frame size ($+0.20$).

²⁾ K, S hole's positional tolerance is based on the central line of shaft extension 0

³⁾ Dimension of P is the maximum limit

⁴⁾ R is the distance from the flange to the drive shaft end.



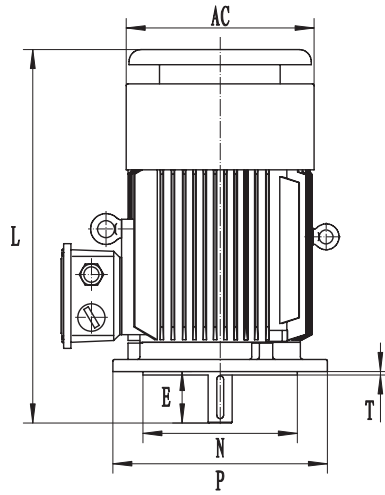
FS 80 ~ 200 (1LG0080...1LG0207)

FS 225 ~ 250 (1LG0220...1LG0253)

mm

											Contour Dimensions				
M	N		P ³⁾	R ⁴⁾		S ²⁾			T	Flange hole number	DB	AC	HF	L	
165	130	+0.014 -0.011	200	0	±1.5	12	+0.430 0	φ 1.0 (M)	3.5	0 -0.120	4	M6	164	235	355
			250									±2.0	15	4	M8
215	180	+0.016 -0.013	300	±3.0	19	+0.520 0	φ 1.5 (M)	5	8	M10		204	290	445	
265	230									±4.0		M12	267	360	530
300	250	±0.016	350	M16	325	480	685								
350	300	±0.018	400	M20	366	510	735								
400	350	±0.020	450	408	570	840									
500	450	±0.018	550	456	615	885									
				504	685	915									
						995									

Dimension drawings



FS 280 ~ 355 (1LG0280...1LG0357)

Table 4 (Continuous) Vertically-mounted, Frame without feet and with flange (with through holes) on the end shield, shaft extension downwards

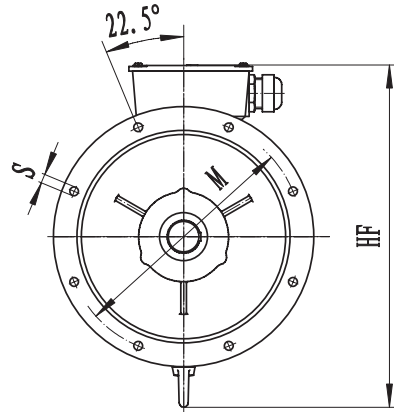
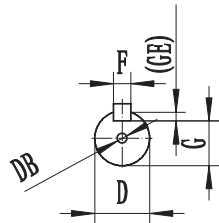
Frame size		Flang number	Poles	Mounting Dimensions and Tolerance							
				D		E	F		G ¹⁾		
280S	1LG0280	FF500	2		±0.500	140	18	0 -0.043	58	0 -0.20	
			4, 6	75			20	0 -0.052	67.5		
280M	1LG0283		2	65			18	0 -0.043	58		
			4, 6	75			20	0 -0.052	67.5		
315S	1LG0310	FF600	2	65	±0.030 +0.011	140	18	0 -0.043	58		
			4, 6	80			22	0 -0.052	71		
315M	1LG0313		2	65			170	18	0 -0.043		58
			4, 6	80				22	0 -0.052		71
315L	1LG0316...1LG0317		2	65			140	18	0 -0.043		58
			4, 6	80				22	0 -0.052		71
355M	1LG0353...1LG0355	2	75	140	20	0 -0.052	67.5				
		4, 6	95		+0.035 +0.013		25	86			
355L	1LG0356...1LG0357	2	75	+0.030 +0.011	140	20	67.5				
		4, 6	95	+0.035 +0.013	170	25	86				

¹⁾ G=D-GE, GE limit deviations for frame size 80M (1LG0080...1LG0083) are ($+0.10$), for other frame size ($+0.20$).

²⁾ K, S hole's positional tolerance is based on the central line of shaft extension 0

³⁾ Dimension of P is the maximum limit

⁴⁾ R is the distance from the flange to the drive shaft end.



FS 280 ~ 355 (1LG0280...1LG0357)

mm

											Contour Dimensions			
M	N		P ³⁾	R ⁴⁾		S ²⁾		T	Flange hole number	DB	AC	HF	L	
500	450	±0.022	550	0	±4.0	19	φ 1.5 (M)	5	0 -0.120	M20	566	760	1040	
													1060	
						1090								
						1110								
600	550	±0.022	660	0	±4.0	24	φ 2.0 (M)	6	0 -0.150		M20	639	950	1270
														1300
						1380								
						140								
740	680	±0.025	800	0	±4.0	24	φ 2.0 (M)	6	0 -0.150	M24		718	1125	1380
														1440
														1580
740	680	±0.025	800	0	±4.0	24	φ 2.0 (M)	6	0 -0.150	M20		718	1125	1610
											1580			
											1610			

Certificates



ATTESTATION OF CONFORMITY WITH EUROPEAN DIRECTIVE

Order No. 75053

A sample of the following product has been tested and is stated by Nemko to be in conformity with the applicable European safety- and EMC standards referred below.

Manufacturer	Siemens Standard Motors Ltd. 110 West Street, Qingshan Town Yizheng City P.R. CHINA
Product	Three-phase Induction Motors
Model/type	1LG0abc
Data	220/380V~ alt. 380/660V~, 50Hz or 440V~, 60Hz; 0.55kW-315kW
Other specification	IP55, 2/4/6P; Frame size 80-355mm
Standards applied	Safety std.: EN 60034-1:2004 EN 60034-5:2001 EMC std.: EMC is based on self-declaration by the manufacturer
Statement reference	75053

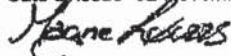
It may therefore be presumed that the tested sample of the product is in conformity with the technical provisions of the following European Directives including the latest amendments, and with national legislation implementing these Directives:

- Low Voltage Directive 73/23/EEC
- EMC Directive 89/336/EEC

On this basis, the manufacturer (or the European authorized representative), may draw up an EC/EEA Declaration of Conformity and affix the CE-marking as indicated below to each conforming product.

Additional information Description of type reference:
abc = frame size: 080-355

Date of issue 02 November 2006


signature

Magne Løvaas
Head of section



Nemko AS
P.O. Box 73, Blindern
N-0314 Oslo, Norway

Office address
Gaustadalléen 30
Oslo

Telephone
+47 22 96 03 30
Enterprise number:

Fax
+47 22 98 05 50
NO 974404532

Certificates



THE INTERNATIONAL CERTIFICATION NETWORK

CERTIFICATE

IQNet and
CQC
hereby certify that the organization

Siemens Standard Motors Ltd.

**No.110, West Street, Qingshan Town, Yizheng City, Jiangsu Prov.,
P.R.China**

For the following field of activities
**Design, Production and Service of Three-phase Asynchronous Motor
(H63-355)**

Has implemented and maintains a
Management System
Which fulfils the requirements of the following standard
ISO9001:2000

Issued on: Jul. 13, 2009
Validity date: Jul. 12, 2012
Registration Number: **00109Q19009R2L/3200**


René Wasmer
René Wasmer
President of IQNet


Wang Kejiao
President of CQC



IQNet Partners*:
AENOR Spain AFNOR Certification France AIB-Vincotte International Belgium ANCE Mexico APCER Portugal CISQ Italy
CQC China CQM China CQS Czech Republic Cro Cert Croatia DQS Holding GmbH Germany DS Denmark ELOT Greece
FCAV Brazil FONDONORMA Venezuela HKQAA Hong Kong China ICONTEC Colombia IMNC Mexico Inspecta Certification Finland
IRAM Argentina JQA Japan KFQ Korea MSZT Hungary Nemko AS Norway NSAI Ireland PCBC Poland
Quality Austria Austria RR Russia SII Israel SIO Slovenia SIRIM OAS International Malaysia SOS Switzerland SRAC Romania

Siemens Ltd., China
Industry Sector
Industry Automation & Drive Technologies

www.ad.siemens.com.cn

Order NO. E20001-A-0132-C600-X-7600
658-SH905830-02105

The information provided in this catalogue contains merely general descriptions or characteristics of performance which in actual case of use do not always apply as described or which may change as a result of further development of the products. An obligation to provide the respective characteristics shall only exist if expressly agreed in the terms of contract.

All product designations may be trademarks or product names of Siemens or supplier companies whose use by third parties for their own purposes could violate the rights of the owners.